**Computational Robotic 2023 - SC. Department**

Presented to: Dr. Mohammed Marey

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| **Evaluation points** | | |
| **1** | **reading** |  |
| **2** | **examples** |  |
| **3** | **practical (source code example)** |  |
| **4** | **system architecture & robot platform** |  |
| **5** | **sensors and its data** |  |
| **6** | **idea (approaches and methods)** |  |
| **7** | **understanding ( approaches and methods)** |  |
| **8** | **Applications** |  |
| **9** | **presenting the work** |  |
| **10** | **References** |  |

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| --- | --- | --- |
| Published year | Paper title | No. of citation |
| Write the published year | Write the paper title | Write the citation number of the paper (you can find it from Google scholar) |

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| **Presented by: Team Members** | | |
| **ID** | **Name** | **Tasks (Contributions)** |
| Write ID | Write name | Write task(s) done by a member |
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| The code | | |
| Paper related | | Course related |
| Complete code of the paper | Part of the code of the paper | Write topic 1 |
| Write topic 2 |
| Write topic 3 |
| Write topic 4 |

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| Paper main idea |
| Write the main points that are represented in the paper.  1. System architecture & robot platform  2. Idea (approaches and methods)  3. Sensors and its data  4. Applications  5. Implementation methodology  6. What are the related topics from the lectures used in the |